# ARTIFICIAL INTELLIGENCE LAB MANUAL



## BALAJI INSTITUTE OF TECHNOLOGY AND SCIENCE (AUTONOMOUS)

**DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING** 

## **BALAJI INSTITUTE OF TECHNOLOGY & SCIENCE**

## (AUTONOMOUS)

22CS648PC: ARTIFICIAL INTELLIGENCE LAB (SYLLABUS)

## **Course Objectives:**

 Become familiar with basic principles of AI toward problem solving, knowledge representation, and learning.

## **Course Outcomes:**

• Apply basic principles of AI in solutions that require problem solving, knowledge representation, and learning.

## **List of Experiments:**

Write a Program to Implement the following using Python.

- 1. BFS, DFS Search Strategy
- 2. Tic-Tac-Toe game
- 3. 8-Puzzle problem
- 4. Water-Jug problem
- 5. Travelling Salesman Problem
- 6. Tower of Hanoi
- 7. Monkey Banana Problem
- 8. Al Web Robot: Wayback Machine case study project
- 9. 8-Queens Problem

```
1. Write a program to implement the following
a) DFS.
b) BFS.
a) A Program to implement DFS
graph={
  'A':['B', 'C'],
  'B':['D','E'],
  'C':['F'],
  'D':[],
  'E':['F'],
  'F':[]
}
visited = set()
def dfs(visited, graph, node):
  if node not in visited:
     print(node,end="")
     visited.add(node)
     for neighbour in graph[node]:
       dfs(visited, graph, neighbour)
dfs(visited, graph, 'A')
output: ABDEFC
```

## b) A program to implement BFS Algorithm

```
graph={
  'A':['B', 'C'],
  'B':['D','E'],
  'C':['F'],
  'D':[],
  'E':['F'],
  'F':[]
}
visited = []
queue = []
def bfs(visited, graph, node):
  visited.append(node)
  queue.append(node)
  while queue:
     s=queue.pop(0)
     print(s, end=" ")
     for neighbour in graph[s]:
       if neighbour not in visited:
          visited.append(neighbour)
          queue.append(neighbour)
bfs(visited, graph, 'A')
```

Output: ABCDEF

## 2. Write a program to implement Tic-Tac-Toe Game

"""Checks if the game is a draw."""

if all(board[i][j] in ['X', 'O'] for i in range(3) for j in range(3)):

# Tic-Tac-Toe Game with 3 consecutive marks to win def print\_board(board): """Prints the Tic-Tac-Toe board.""" for row in board: print(" | ".join(row)) print("-" \* 9) def check\_winner(board, player): """Checks if a player has won with 3 consecutive marks in a row, column, or diagonal.""" # Check rows-horizontal and columns-vertical for i in range(3): if all(board[i][j] == player for j in range(3)) or all(board[j][i] == player for j in range(3)): return True # Check diagonals if all(board[i][i] == player for i in range(3)) or all(board[i][2 - i] == player for i in range(3)): return True return False def is\_draw(board):

```
return True
  else:
     return False
def get_move(board, player):
  """Gets a valid move from the player."""
  while True:
     try:
       move = int(input(f"Player {player}, enter your move (1-9): ")) - 1
       row, col = divmod(move, 3)
       if 0 \le move < 9 and board[row][col] == '':
          return row, col
       else:
          print("Invalid move! That spot is already taken.")
     except ValueError:
       print("Invalid input! Enter a number between 1 and 9.")
def play_game():
  """Main function to play the game."""
  board = [[' ' for _ in range(3)] for _ in range(3)]
  players = ['X', 'O']
  turn = 0
  print("Welcome to Tic-Tac-Toe!")
  print_board(board)
```

```
while True:
    player = players[turn % 2]
    row, col = get_move(board, player)
    board[row][col] = player
    print_board(board)
    if check_winner(board, player):
       print(f"Player {player} wins!")
       break
    elif is_draw(board):
       print("It's a draw!")
       break
    turn = turn + 1
# Run the game
play_game()
Output:
Welcome to Tic-Tac-Toe!
| \cdot |
-----
```

Player X, enter your move (1-9): 5
1.1
X
1 1
Player O, enter your move (1-9): 1
0
X
1 1
Player X, enter your move (1-9): 2
O   X
X
1.1

Player O, enter your move (1-9): 3
O   X   O
X
Player X, enter your move (1-9): 8
O   X   O
X
X
Player X wins!

## 4. Write a program to implement 8 Puzzle Problem

from collections import deque

return neighbors

```
def is_solvable(board):
  flat board = [num for row in board for num in row]
  inversions = sum(
     1 for i in range(len(flat_board)) for j in range(i + 1, len(flat_board))
     if flat_board[i] and flat_board[j] and flat_board[i] > flat_board[j]
  )
  return inversions % 2 == 0
def get_neighbors(board):
  neighbors = []
  x, y = [(i, j) \text{ for } i \text{ in } range(3) \text{ for } j \text{ in } range(3) \text{ if } board[i][j] == 0][0]
  directions = [(-1, 0), (1, 0), (0, -1), (0, 1)]
  for dx, dy in directions:
     nx, ny = x + dx, y + dy
     if 0 \le nx \le 3 and 0 \le ny \le 3:
        new_board = [row[:] for row in board]
        new_board[x][y], new_board[nx][ny] = new_board[nx][ny], new_board[x][y]
        neighbors.append(new_board)
```

```
def solve_puzzle(start_board):
  goal_state = [[0, 1, 2], [3, 4, 5], [6, 7, 8]]
  queue = deque([(start_board, [])])
  visited = set()
  visited.add(tuple(map(tuple, start_board)))
  while queue:
     board, path = queue.popleft()
     if board == goal_state:
       return path + [board]
     for neighbor in get_neighbors(board):
       board_tuple = tuple(map(tuple, neighbor))
       if board_tuple not in visited:
          visited.add(board_tuple)
          queue.append((neighbor, path + [board]))
  return None
def print_puzzle_path(path):
  for step, board in enumerate(path):
     print(f"Step {step}:")
     for row in board:
       print(row)
     print()
```

```
# Example usage
initial_state = [[1, 2, 5], [3, 4, 0], [6, 7, 8]]
if is_solvable(initial_state):
  solution_path = solve_puzzle(initial_state)
  if solution_path:
     print_puzzle_path(solution_path)
  else:
     print("No solution found.")
else:
  print("Puzzle is not solvable.")
Output:
Step 0:
[1, 2, 5]
[3, 4, 0]
[6, 7, 8]
Step 1:
[1, 2, 0]
[3, 4, 5]
[6, 7, 8]
Step 2:
```

[1, 0, 2]

- [3, 4, 5]
- [6, 7, 8]

## Step 3:

- [0, 1, 2]
- [3, 4, 5]
- [6, 7, 8]

## 4. Write a program to implement Water Jug Problem

```
#jug1 capacity = 5; jug2 cap = 3
def water_jug_problem(a, b, target):
  # Check if the target is achievable
  if target > max(a, b):
     print("Target is greater than both jug capacities")
     return False
  # Use a set to keep track of visited states (amount of water in each jug)
  visited = set()
  # Create a queue to simulate the process (state: (amount in jug 1, amount in jug 2))
  queue = [(0, 0)] # Start with both jugs empty
  while queue:
    jug1, jug2 = queue.pop(0)
     print(jug1,end=",")
     print(jug2)
     # If the target is reached, return True
     if jug1 == target or jug2 == target:
       return True
```

# List all possib actions: fill jug1, fill jug2, empty jug1, empty jug2, transfer from jug1 to jug2, and transfer from jug2 to jug1

```
possible_states = [
       (a, jug2), #Fill jug1
       (jug1, b), #Fill jug2
       (0, jug2), #Empty jug1
       (jug1, 0), #Empty jug2
       (jug1 - min(jug1, b - jug2), jug2 + min(jug1, b - jug2)), # Transfer from jug1 to jug2
       (jug1 + min(jug2, a - jug1), jug2 - min(jug2, a - jug1)) # Transfer from jug2 to jug1
     ]
     # Check each new state, add it to the queue if it's not visited
     for state in possible_states:
       if state not in visited:
          visited.add(state)
          queue.append(state)
  return False
# Example usage main program
a = 5 \# Jug 1 capacity
b = 3 \# Jug 2 capacity
target = 4 # Target amount of water
if water_jug_problem(a, b, target):
  print("Target is achievable!")
else:
  print("Target is not achievable.")
```

# Output: 0,0 5,0 0,3 0,0 5,3 2,3 3,0 2,0 3,3 0,2 5,1 5,2

Target is achievable!

0,1

4,3

## 5. Write a program to implement Travelling Salesman Problem.

from itertools import permutations

```
# Distance matrix representing the cost between cities
distance_matrix = [
  [0, 10, 15, 20], # Distances from city 0
  [10, 0, 35, 25], # Distances from city 1
  [15, 35, 0, 30], # Distances from city 2
  [20, 25, 30, 0] # Distances from city 3
]
num_cities = len(distance_matrix)
cities = list(range(num_cities)) # List of city indices
def calculate_route_distance(route):
  """Calculate the total distance of a given route."""
  total\_distance = 0
  for i in range(len(route) - 1):
     total_distance += distance_matrix[route[i]][route[i + 1]]
  total_distance += distance_matrix[route[-1]][route[0]] # Returning to start
  return total distance
# Brute-force approach: Try all possible city orderings
min_distance = float('inf')
best route = None
```

```
for perm in permutations(cities[1:]): # Fix city 0 as the start point

route = (0,) + perm # Start from city 0

dist = calculate_route_distance(route)

if dist < min_distance:

min_distance = dist

best_route = route

# Output the best route and distance

print("Best Route:", " -> ".join(map(str, best_route)), "-> 0")

print("Minimum Distance:", min_distance)

Output:

Best Route: 0 -> 1 -> 3 -> 2 -> 0
```

Minimum Distance: 80

## 6. Write a program to implement Towers of Hanoi

```
class Tower:
   def __init__(self):
      self.terminate = 1
   def printMove(self, source, destination):
      print("{} -> {}".format(source, destination))
   def move(self, disc, source, destination, auxiliary):
      if disc == self.terminate:
         self.printMove(source, destination)
      else:
         self.move(disc - 1, source, auxiliary, destination)
         self.move(1, source, destination, auxiliary)
         self.move(disc - 1, auxiliary, destination, source)
t = Tower();
t.move(3, 'A', 'B', 'C')
Output:
A \rightarrow B
A \rightarrow C
B \rightarrow C
A \rightarrow B
C \rightarrow A
C \rightarrow B
A \rightarrow B
```

## 7. Write a program to implement Monkey-Banana Problem

class MonkeyBananaBoxProblem: def \_\_init\_\_(self): # The monkey starts on the ground (height 0)  $self.monkey\_height = 0$ # The box starts at position 0 and must be moved to the correct position under the banana  $self.box_position = 0$ # The banana is hanging at height 3  $self.banana_height = 3$ # The box is initially on the ground (height 1)  $self.box\_height = 1$ def can\_reach\_banana(self): # The monkey can reach the banana if it is at or above the height of the banana return self.monkey\_height >= self.banana\_height def move\_box(self): # Move the box closer to the banana (stop when it's directly under the banana) if self.box\_position < self.banana\_height - 1: self.box\_position += 1 print(f"Box moved to position: {self.box\_position}") else: print("Box is positioned under the banana.") # Set the box height to be directly beneath the banana self.box\_height = self.banana\_height - 1

```
def climb_box(self):
    # The monkey climbs the box, increasing its height by 1
     self.monkey\_height = self.box\_height + 1
    print(f"Monkey climbs the box! Current height: {self.monkey_height}")
  def attempt_to_get_banana(self):
    # Try to get the banana, check if the monkey is at or above the banana's height
    if self.can_reach_banana():
       print("Monkey has reached the banana and got it!")
     else:
       print("Monkey cannot reach the banana. Moving the box.")
       # Move the box toward the banana until it is positioned beneath it
       self.move_box()
       # Once the box is beneath the banana, the monkey climbs on top of it
       if self.box_position == self.banana_height - 1:
         self.climb_box()
       # After climbing, the monkey attempts to get the banana again
       self.attempt_to_get_banana()
# Instantiate the problem
problem = MonkeyBananaBoxProblem()
```

# Start the process of attempting to get the banana problem.attempt\_to\_get\_banana()

## **Output:**

Monkey cannot reach the banana. Moving the box.

Box moved to position: 1

Monkey cannot reach the banana. Moving the box.

Box moved to position: 2

Monkey climbs the box! Current height: 2

Monkey cannot reach the banana. Moving the box.

Box is positioned under the banana.

Monkey climbs the box! Current height: 3

Monkey has reached the banana and got it!

## 8. Write a program to implement AI Web Robot: Wayback Machine Case Study

import requests

```
def get_wayback_snapshots(url):
  *****
  Fetch archived snapshots of a given URL from the Wayback Machine.
  ,,,,,,
  base_url = "http://web.archive.org/cdx/search/cdx"
  params = {
     "url": url,
     "output": "json",
     "fl": "timestamp,original",
     "collapse": "timestamp",
  }
  try:
     response = requests.get(base_url, params=params)
     response.raise_for_status()
     data = response.json()
     if len(data) > 1:
       return data[1:] # Exclude the header row
     else:
       print("No archives found for this URL.")
       return []
```

```
except requests.exceptions.RequestException as e:
    print("Error fetching data:", e)
    return []
def get_latest_archive(url):
  Fetch the latest archived version of the given URL.
  *****
  snapshots = get_wayback_snapshots(url)
  if snapshots:
     latest_snapshot = snapshots[-1] # Get the most recent entry
     timestamp, archived_url = latest_snapshot
     archived_url = f"http://web.archive.org/web/{timestamp}/{archived_url}"
     return archived_url
  else:
     return None
# Script executes automatically
website_url = input("Enter the website URL to check Wayback Machine archives: ")
# Fetch and display snapshots
snapshots = get_wayback_snapshots(website_url)
if snapshots:
  print("\nAvailable Snapshots:")
```

```
for timestamp, original in snapshots[:5]: # Display first 5 snapshots

print(f'Date: {timestamp[:4]}-{timestamp[4:6]}-{timestamp[6:8]}, Link:
http://web.archive.org/web/{timestamp}/{original}'')

# Get and display the latest archive
latest_archive = get_latest_archive(website_url)

if latest_archive:

print("\nLatest Archived Version:", latest_archive)

else:
```

## **Output:**

Enter the website URL to check Wayback Machine archives: example.com

print("\nNo archived version found.")

Available Snapshots:

Date: 1998-12-06, Link: http://web.archive.org/web/19981206052836/http://example.com

Date: 2001-02-08, Link: http://web.archive.org/web/20010208083200/http://example.com

Date: 2005-07-22, Link: http://web.archive.org/web/20050722041041/http://example.com

Latest Archived Version: http://web.archive.org/web/20240315000000/http://example.com

## 9. Write a program to implement 8 Queens Problem

```
N = 8 # Size of the chessboard (8x8)
# Function to print the chessboard configuration
def print_board(board):
  for row in board:
     for col in row:
       print("Q " if col == 1 else ". ", end="")
     print()
# Function to check if a queen can be placed at board[row][col]
def is_safe(board, row, col):
  # Check the column
  for i in range(row):
     if board[i][col] == 1:
       return False
  # Check the left diagonal
  for i, j in zip(range(row - 1, -1, -1), range(col - 1, -1, -1)):
     if board[i][j] == 1:
       return False
  # Check the right diagonal
  for i, j in zip(range(row - 1, -1, -1), range(col + 1, N)):
     if board[i][j] == 1:
```

```
return False
```

return True # Function to solve the 8-Queens problem using backtracking def solve\_n\_queens(board, row): if row == N: return True # All queens are placed # Try placing a queen in each column of the current row for col in range(N): if is\_safe(board, row, col): board[row][col] = 1 # Place the queen # Recur to place the next queen if solve\_n\_queens(board, row + 1): return True # If placing queen doesn't lead to a solution, backtrack board[row][col] = 0 # Remove the queen (backtrack) return False # If no queen can be placed in any column

# Main function to solve the 8-Queens problem and print the solution def main():

```
board = [[0 for _ in range(N)] for _ in range(N)] # Initialize the chessboard with 0's
  if solve_n_queens(board, 0):
     print_board(board) # Print the solution
  else:
     print("Solution does not exist.")
main()
Output:
Q . . . . . . .
. . . . Q . . .
. . . . . . Q
.....Q...
. . Q . . . . .
. . . . . . Q .
. Q . . . . .
...Q....
```

## **Programs beyond the Syllabus**

## 1. Write a program to find the solution for wampus world problem

import random

```
# Define the 4x4 grid environment
size = 4
world = [[' ' for _ in range(size)] for _ in range(size)]
# Place Wumpus, Pit, and Gold at random positions
def place_randomly(symbol):
  while True:
     x, y = random.randint(0, size - 1), random.randint(0, size - 1)
    if world[x][y] == '' and (x, y) != (0, 0): # Ensure agent's starting position is safe
       world[x][y] = symbol
       return (x, y)
wumpus_pos = place_randomly('W')
pit_pos = place_randomly('P')
gold_pos = place_randomly('G')
# Agent starts at (0,0)
agent x, agent y = 0, 0
# Function to display the world
def display_world():
```

```
for row in world:
    print('|'.join(row))
  print("\n")
# Game loop
while True:
  print(f"Agent is at ({agent_x}, {agent_y})")
  # Check surroundings
  if (agent_x, agent_y) == wumpus_pos:
    print("Game Over! The Wumpus ate you!")
     break
  elif (agent_x, agent_y) == pit_pos:
     print("Game Over! You fell into a pit!")
     break
  elif (agent_x, agent_y) == gold_pos:
    print("Congratulations! You found the gold!")
     break
  # Move agent
  move = input("Move (W/A/S/D): ").upper()
  if move == 'W' and agent_x > 0:
     agent_x -= 1
  elif move == 'S' and agent_x < size - 1:
     agent_x += 1
```

```
elif move == 'A' and agent_y > 0:
    agent_y -= 1
elif move == 'D' and agent_y < size - 1:
    agent_y += 1
else:
    print("Invalid move! Try again.")

Output:
Agent is at (0, 0)
Move (W/A/S/D): S
Agent is at (1, 0)
Move (W/A/S/D): D
Agent is at (1, 1)</pre>
```

Game Over! The Wumpus ate you!

## 2. Write a program to implement Hill Climbing Algorithm

import random

```
# Define the function to maximize
def objective_function(x):
  return -(x - 3) ** 2 + 9 # A simple quadratic function
# Hill Climbing Algorithm
def hill_climb(start_x, step_size=0.1, max_iterations=100):
  current_x = start_x # Start at a random point
  current_value = objective_function(current_x)
  for _ in range(max_iterations):
    # Generate neighbors (small changes in x)
     new_x = current_x + random.choice([-step_size, step_size])
     new_value = objective_function(new_x)
     # If the new value is better, move to new_x
     if new_value > current_value:
       current_x, current_value = new_x, new_value
     else:
       break # Stop if no improvement
  return current_x, current_value
```

# Run Hill Climbing from a random starting point

```
start = random.uniform(0, 5) # Start in the range [0,5]
best_x, best_value = hill_climb(start)

# Print the result
print(f"Starting Point: {start:.2f}")
print(f"Optimal x: {best_x:.2f}, Maximum Value: {best_value:.2f}")
```

## **Output:**

Starting Point: 4.12

Optimal x: 3.00, Maximum Value: 9.00

## 3. Write a program to implement A\* Algorithm

from queue import PriorityQueue

```
# Define the grid (0 = \text{free space}, 1 = \text{obstacle})
grid = [
  [0, 1, 0, 0, 0],
  [0, 1, 0, 1, 0],
  [0, 0, 0, 1, 0],
  [1, 1, 0, 1, 0],
  [0, 0, 0, 0, 0]
]
# Define possible movements (up, down, left, right)
moves = [(0, 1), (1, 0), (0, -1), (-1, 0)]
# Heuristic function (Manhattan Distance)
def heuristic(a, b):
  return abs(a[0] - b[0]) + abs(a[1] - b[1])
# A* Algorithm
def astar(start, goal):
  open_set = PriorityQueue()
  open_set.put((0, start)) # (priority, node)
  came_from = {} # Store the path
```

```
g_score = {start: 0} # Cost from start
  f_score = {start: heuristic(start, goal)} # Estimated total cost
  while not open_set.empty():
     _, current = open_set.get()
     if current == goal:
       # Reconstruct path
        path = []
        while current in came_from:
          path.append(current)
          current = came_from[current]
        path.append(start)
        return path[::-1] # Return reversed path
     # Explore neighbors
     for move in moves:
        neighbor = (current[0] + move[0], current[1] + move[1])
       # Check if neighbor is within bounds and not an obstacle
        if 0 \le \text{neighbor}[0] \le \text{len}(\text{grid}) and 0 \le \text{neighbor}[1] \le \text{len}(\text{grid}[0]) and
grid[neighbor[0]][neighbor[1]] == 0:
          temp\_g\_score = g\_score[current] + 1
          if neighbor not in g_score or temp_g_score < g_score[neighbor]:
```

```
g_score[neighbor] = temp_g_score
            f_score[neighbor] = temp_g_score + heuristic(neighbor, goal)
            open_set.put((f_score[neighbor], neighbor))
            came_from[neighbor] = current
  return None # No path found
# Define start and goal positions
start = (0, 0)
goal = (4, 4)
# Run A* Algorithm
path = astar(start, goal)
# Print result
if path:
  print("Path found:", path)
else:
  print("No path found.")
Output:
Path found: [(0, 0), (1, 0), (2, 0), (2, 1), (2, 2), (3, 2), (4, 2), (4, 3), (4, 4)]
```